
EXISTENCE OF SOLUTIONS OF BOUNDARY VALUE
PROBLEMS FOR THE EQUATION $f(t, x, x', x'') = 0$
WITH FULLY NONLINEAR BOUNDARY CONDITIONS

PETIO KELEVEDJIEV, NEDYU POPIVANOV

Existence results for two-point boundary value problems are established, the equation is not solved with respect to the high derivative, and the boundary conditions are nonlinear and full. The proofs are based on a variant of a basic theorem of Granas, Guenther and Lee. The a priori bounds needed for its application are obtained by the barrier strips technique.

Keywords: boundary value problems, nonlinear boundary conditions, existence, barrier strips

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1. INTRODUCTION

In this paper we study the solvability of boundary value problems (BVPs) of the form

$$\begin{cases} f(t, x, x', x'') = 0, & t \in [0, 1], \\ W_i(x) = V_i(x), & i = 1, 2. \end{cases} \quad (1.1)$$

Here the scalar function $f(t, x, p, q)$ is continuous and has continuous first derivatives only on suitable subsets of $[0, 1] \times R^3$,

$$V_1(x) = \varphi(x(0), x'(0), x(1), x'(1)), \quad V_2(x) = \psi(x(0), x'(0), x(1), x'(1)),$$

$\phi, \psi : R^4 \rightarrow R$ are continuous, and $(W_1(x), W_2(x))$ are of the type

$$(M_1)(x(0), x'(1)), \quad (M_2)(x'(0), x(1)) \quad \text{or} \quad (D)(x(0), x(1)).$$

Further, we will write as (M_1) , (M_2) and (D) the BVP (1.1) in the cases (M_1) , (M_2) and (D) , respectively.

The solvability of BVPs for the equation $x'' = f(t, x, x')$ with various nonlinear boundary conditions is studied in [1–8], for example, under various conditions on $f(t, x, p)$.

The results [9–14], see also [15], guarantee the existence of $C^2[0, 1]$ -solutions to BVPs for the equation $x'' = f(t, x, x', x'') - y(t)$. Moreover, the solutions satisfy mixed boundary conditions (M_1) or (M_2) in [9], periodic ones in [10], Neumann ones in [9, 11], Dirichlet or periodic ones in [9, 12, 13], and either Dirichlet, Neumann, Sturm-Liouville, periodic or antiperiodic ones in [14]; in the last work uniqueness results are also obtained. Moreover, the growth of $f(t, x, p, q)$ is linear with respect to x, p and q in [10–12], semilinear in [13], quadratic with respect to p and linear with respect to q in [14]. In addition f satisfies various further conditions. The results [16] guarantee an existence and an uniqueness of $C^2[0, 1]$ -solution to the BVP for the equation $x'' = f(t, x, x', x'')$ with boundary conditions of the form

$$a_{i1}x(0) + a_{i2}x'(0) + a_{i3}x(1) + a_{i4}x'(1) = 0, i = 1, 2.$$

In [16] $f(t, x, p, q)$ satisfies a growth condition, which is a Nagumo one with respect to p and a linear one with respect to q , and some further conditions. The approach [10–14, 16] relies on the topological transversality [8] or similar arguments. The existence results [17] guarantee $W^{2,\infty}[0, 1]$ -solutions or $C^2[0, 1]$ -solutions to the Dirichlet BVP for the equation (1.1). The function $f(t, x, p, q)$ is defined on $[0, 1] \times R^n \times R^n \times Y$, where Y is a non-empty closed connected and locally connected subset of R^n . Growth conditions on f are not used. The approach [17] follows that introduced in [18] with regard to the Cauchy problem. The results [19] guarantee an existence of $C^2[0, 1]$ -solutions to the BVP for the equation $x'' + g(t, x, x', x'') = y(t)$ with either Dirichlet, Neumann or mixed boundary conditions. The authors use conditions of Lipschitz type on g and barrier strips [20].

In this paper we also do not use assumptions on the growth of f . Using again the barrier strips technique [20], see also [19] for similar conditions, we obtain some uniformly a priori bounds for x', x and x'' (in this order) for the eventual solutions $x(t) \in C^2[0, 1]$ to the family of BVPs

$$\begin{cases} Kx'' &= \lambda(Kx'' + f(t, x, x', x'')), & t \in [0, 1], \\ W_i(x) &= \lambda V_i(x), & i = 1, 2, \end{cases} \quad (1.1)_\lambda$$

where $\lambda \in [0, 1]$, and K is a suitable positive constant; further, we will write as $(M_1)_\lambda$, $(M_2)_\lambda$ and $(D)_\lambda$ the family $(1.1)_\lambda$ in the cases (M_1) , (M_2) and (D) , respectively. Then the solvability of the problems considered follows by a basic existence result (Theorem 4.1) proved by an application of the topological transversality theorem [8].

2. HYPOTHESES

We will say that (A_1) holds for the constants F and L if:

(A_1) $L \geq F$ and there are functions $F_i^-(t), L_i^+(t) \in C[0, 1], i = 1, 2$, such that

$$L_1^+(1) \geq L, F \geq F_1^-(1),$$

$L_1^+(t)$ is nonincreasing and $F_1^-(t)$ is nondecreasing on $[0, 1]$,

$$L_2^+(t) > L_1^+(t) \quad \text{and} \quad F_1^-(t) > F_2^-(t) \quad \text{for } t \in [0, 1],$$

and there is a constant $K > 0$ for which

$$f(t, x, p, q) \geq -Kq$$

on $\{(t, x, p, q) : x \in R, q \in (-\infty, 0), t \in [0, 1] \text{ and } L_1^+(t) \leq p \leq L_2^+(t)\}$,

$$f(t, x, p, q) \leq -Kq$$

on $\{(t, x, p, q) : x \in R, q \in (0, \infty), t \in [0, 1] \text{ and } F_2^-(t) \leq p \leq F_1^-(t)\}$.

We will say that (A_2) holds for the constants F and L if:

(A_2) $L \geq F$ and there are functions $F_i^+(t), L_i^-(t) \in C[0, 1], i = 1, 2$, such that

$$L_1^-(0) \geq L, F \geq F_1^+(0),$$

$L_1^-(t)$ is nondecreasing and $F_1^+(t)$ is nonincreasing on $[0, 1]$,

$$L_2^-(t) > L_1^-(t) \quad \text{and} \quad F_1^+(t) > F_2^+(t) \quad \text{for } t \in [0, 1],$$

and there is a constant $K > 0$ for which

$$f(t, x, p, q) \leq -Kq$$

on $\{(t, x, p, q) : x \in R, q \in (0, \infty), t \in [0, 1] \text{ and } L_1^-(t) \leq p \leq L_2^-(t)\}$,

$$f(t, x, p, q) \geq -Kq$$

on $\{(t, x, p, q) : x \in R, q \in (-\infty, 0), t \in [0, 1] \text{ and } F_2^+(t) \leq p \leq F_1^+(t)\}$.

Remark. The constant K from (A_1) and the constant K from (A_2) could be different.

Lemma 2.1. *Let the condition (A_1) hold for some F and L and $x(t) \in C^2[0, 1]$ be a solution to (1.1) $_\lambda$ (with the constant K from (A_1)). Suppose there is an interval $T_1 \subseteq [0, 1]$ such that*

$$L_1^+(t) \leq x'(t) \leq L_2^+(t) \quad \text{for } t \in T_1. \tag{2.1}$$

Then $x''(t) \geq 0$ for $t \in T_1$. If there is an interval $T_2 \subseteq [0, 1]$ such that

$$F_2^-(t) \leq x'(t) \leq F_1^-(t) \quad \text{for } t \in T_2,$$

then $x''(t) \leq 0$ for $t \in T_2$.

Proof. We will show only that (2.1) yields $x''(t) \geq 0$ for $t \in T_1$. The assertion is true for $\lambda = 0$. Now let $\lambda \in (0, 1]$. Assume there is $t_0 \in T_1$ such that $x''(t_0) < 0$. Then

$$0 > Kx''(t_0) = \lambda [Kx''(t_0) + f(t_0, x(t_0), x'(t_0), x''(t_0))] \geq 0.$$

The contradiction obtained yields the assertion. \square

Lemma 2.2. *Let the condition (A₂) hold for some F and L and $x(t) \in C^2[0, 1]$ be a solution to (1.1) _{λ} (with the constant K from (A₂)). Suppose there is an interval $T_1 \subseteq [0, 1]$ such that*

$$L_1^-(t) \leq x'(t) \leq L_2^-(t) \quad \text{for } t \in T_1.$$

Then $x''(t) \leq 0$ for $t \in T_1$. If there is an interval $T_2 \subseteq [0, 1]$ such that $F_2^+(t) \leq x'(t) \leq F_1^+(t)$ for $t \in T_2$, then $x''(t) \geq 0$ for $t \in T_2$.

Proof. The proof is the same as for Lemma 2.1 except for a few inessential changes in the details. \square

Denote

$$\max u(t) := \max_{[0,1]} u(t), \quad \min u(t) := \min_{[0,1]} u(t), \quad \text{and} \quad \|u\|_0 := \max |u(t)|.$$

Let $M, Q \in R^+$ be some constants, and $L(t), F(t) \in C[0, 1]$ be some functions such that $L(t) \geq F(t)$ on $[0, 1]$. Let the functions $G_i^-(t), G_i^+(t), H_i^-(t), H_i^+(t) \in C[0, 1], i = 1, 2$, be such that for

$$C = \max \{ \|F\|_0, \|L\|_0 \} \tag{2.2}$$

we have

$$\left\{ \begin{array}{l} G_1^+(t) \geq 2C, G_1^-(t) \geq 2C \text{ for } t \in [0, 1], \\ H_1^+(t) \leq -2C, H_1^-(t) \leq -2C \text{ for } t \in [0, 1], \\ G_1^+(t) \text{ and } H_1^+(t) \text{ are nonincreasing on } [0, 1], \\ G_1^-(t) \text{ and } H_1^-(t) \text{ are nondecreasing on } [0, 1], \\ G_2^+(t) > G_1^+(t), G_2^-(t) > G_1^-(t), \text{ for } t \in [0, 1], \\ H_1^+(t) > H_2^+(t), H_1^-(t) > H_2^-(t) \text{ for } t \in [0, 1]. \end{array} \right. \tag{2.3}$$

Replace

$$Y_1 := \left\{ (t, x, p, q) : |x| \leq M + \varepsilon, t \in [0, 1], p \in [F(t) - \varepsilon, L(t) + \varepsilon] \text{ and} \right.$$

$$\left. q \in \left[\min \{ \min H_2^+(t), \min H_2^-(t) \} - \varepsilon, \max \{ \max G_2^+(t), \max G_2^-(t) \} + \varepsilon \right] \right\},$$

where

$$\left\{ \begin{array}{l} \varepsilon > 0 \text{ is small enough and such that } H_1^+(t) > H_2^+(t) + \varepsilon, \\ H_1^-(t) > H_2^-(t) + \varepsilon, G_1^+(t) > G_2^+(t) + \varepsilon, G_1^-(t) > G_2^-(t) + \varepsilon, \end{array} \right. \tag{2.4}$$

$$\begin{aligned}
Y_2 &:= \left\{ (t, x, p, q) : x \in [-M, M], \text{ and } (t, p, q) \text{ is such that} \right. \\
&\quad \left. t \in [0, 1], p \in [F(t), L(t)], q \in [\min \{H_2^+(t), H_2^-(t)\}, \max \{G_2^+(t), G_2^-(t)\}] \right\} \\
Y_3 &:= \left\{ (t, x, p, q) : x \in [-M, M], \text{ and } (t, p, q) \text{ is such that} \right. \\
&\quad \left. t \in [0, 1], p \in [F(t), L(t)], q \in [H_2^+(t), H_1^+(t)] \cup [G_1^+(t), G_2^+(t)] \right\} \\
Y_4 &:= \left\{ (t, x, p, q) : x \in [-M, M], \text{ and } (t, p, q) \text{ is such that} \right. \\
&\quad \left. t \in [0, 1], p \in [F(t), L(t)], q \in [H_2^-(t), H_1^-(t)] \cup [G_1^-(t), G_2^-(t)] \right\} \\
Y_5 &:= \left\{ (\lambda, t, x, p) : \lambda \in [0, 1], x \in [-Q, Q], t \in [0, 1], p \in [F(t), L(t)] \right\}.
\end{aligned}$$

We will say that **(B)** holds for the functions $L(t), F(t) \in C[0, 1]$ and the constant $M \in R^+$ if:

(B) There are functions $G_i^-(t), G_i^+(t), H_i^-(t), H_i^+(t) \in C[0, 1]$, ($i = 1, 2$), which satisfy (2.3) and are such that

$$\begin{cases} f(t, x, p, q) \text{ and } f_q(t, x, p, q) \text{ are continuous on } Y_1 \\ \text{and } f_q(t, x, p, q) < 0 \text{ on } Y_1, \end{cases} \quad (2.5)$$

$f_t(t, x, p, q), f_x(t, x, p, q)$ and $f_q(t, x, p, q)$ are continuous on Y_2 ,

$$f_t(t, x, p, q) + f_x(t, x, p, q)p + f_p(t, x, p, q)q \geq 0 \text{ on } Y_3,$$

and

$$f_t(t, x, p, q) + f_x(t, x, p, q)p + f_p(t, x, p, q)q \leq 0 \text{ on } Y_4.$$

We will say that **(C)** holds for the functions $L(t), F(t) \in C[0, 1]$ and for the constants $Q \in R^+, Q_1, Q_2$ if:

(C) $F(\lambda, t, x, p, Q_1)F(\lambda, t, x, p, Q_2) \leq 0$ for $(\lambda, t, x, p) \in Y_5$,

where $F(\lambda, t, x, p, q) = (\lambda - 1)Kq + \lambda f(t, x, p, q)$, and K is the constant from (1.1) $_\lambda$.

3. TOPOLOGICAL PRELIMINARIES

For the sake of completeness, we give the topological transversality theorem which will be used later; moreover, we follow [8].

Let X be a metric space, and Y be a convex subset of a Banach space E . The continuous map $F : X \rightarrow Y$ is called compact if $F(X)$ is a compact subset of Y . The continuous map $F : X \rightarrow Y$ is completely continuous if it maps bounded subsets in X into compact subsets of Y .

Theorem 3.1 (Schauder's fixed point theorem). *Let Y be a convex subset of E , and $F : Y \rightarrow Y$ be a compact map. Then there exists a point $x_0 \in Y$ such that $F(x_0) = x_0$.*

We say that the homotopy $\{H_\lambda : X \rightarrow Y\}$, $0 \leq \lambda \leq 1$, is compact if the map $H(x, \lambda) : X \times [0, 1] \rightarrow Y$ given by $H(x, \lambda) \equiv H_\lambda(x)$ for $(x, \lambda) \in X \times [0, 1]$ is compact.

Let $U \subset Y$ be open in Y , ∂U be the boundary of U in Y , and $\bar{U} = \partial U \cup U$. The compact map $F : \bar{U} \rightarrow Y$ is called admissible if it is fixed point free on ∂U . We denote the set of all such maps by $L_{\partial U}(\bar{U}, Y)$.

Definition 3.1. The map F in $L_{\partial U}(\bar{U}, Y)$ is inessential if there is a fixed point free compact map $G : \bar{U} \rightarrow Y$ such that $G|_{\partial U} = F|_{\partial U}$. The map F in $L_{\partial U}(\bar{U}, Y)$, which is not inessential, is called essential.

Theorem 3.2. *Let $p \in U$ be arbitrary and $F \in L_{\partial U}(\bar{U}, Y)$ be the constant map $F(x) = p$ for $x \in \bar{U}$. Then F is essential.*

Proof. Let $G : \bar{U} \rightarrow Y$ be a compact map such that $G|_{\partial U} = F|_{\partial U}$. Define the map $H : Y \rightarrow Y$ by

$$\begin{aligned} H(x) &= p \quad \text{for } x \in Y \setminus \bar{U}, \\ H(x) &= G(x) \quad \text{for } x \in \bar{U}. \end{aligned}$$

Clearly, $H : Y \rightarrow Y$ is a compact map. By Schauder's theorem H has a fixed point $x_0 \in Y$, i. e. $H(x_0) = x_0$. By definition of H we have $x_0 \in U$. Thus, $G(x_0) = x_0$ since H equals G on U . So every compact map from \bar{U} into Y , which agrees with F on ∂U , has a fixed point. That is, F is essential. \square

Definition 3.2. The maps $F, G \in L_{\partial U}(\bar{U}, Y)$ are called homotopic ($F \sim G$) if there is a compact homotopy $H_\lambda : \bar{U} \rightarrow Y$ such that H_λ is admissible for each $\lambda \in [0, 1]$ and $G = H_0, F = H_1$.

Lemma 3.1. *The map $F \in L_{\partial U}(\bar{U}, Y)$ is inessential if and only if it is homotopic to a fixed point free map.*

Proof. Let F be inessential and $G : \bar{U} \rightarrow Y$ be a compact fixed point free map such that $G|_{\partial U} = F|_{\partial U}$. Then the homotopy $H_\lambda : \bar{U} \rightarrow Y$, defined by

$$H_\lambda(x) = \lambda F(x) + (1 - \lambda)G(x), \quad \lambda \in [0, 1],$$

is compact, admissible and such that $G = H_0, F = H_1$.

Now let $H_0 : \bar{U} \rightarrow Y$ be a compact fixed point free map, and $H_\lambda : \bar{U} \rightarrow Y$ be an admissible homotopy joining H_0 and F . To show that $H_\lambda, \lambda \in [0, 1]$, is an

inessential map, consider the map $H : \bar{U} \times [0, 1] \rightarrow Y$ such that $H(x, \lambda) \equiv H_\lambda(x)$ for each $x \in \bar{U}$ and $\lambda \in [0, 1]$ and define the set $B \subset \bar{U}$ by

$$B = \{x \in \bar{U} : H_\lambda(x) \equiv H(x, \lambda) = x \text{ for some } \lambda \in [0, 1]\}.$$

If B is empty, then $H_1 = F$ has no fixed point which means that F is inessential. So we may assume that B is non-empty. In addition, B is closed and such that $B \cap \partial U = \emptyset$ since $H_\lambda, \lambda \in [0, 1]$, is an admissible map. Now consider the Urysohn function $\theta : \bar{U} \rightarrow [0, 1]$ with

$$\theta(x) = 1 \text{ for } x \in \partial U \quad \text{and} \quad \theta(x) = 0 \text{ for } x \in B$$

and define the homotopy $H_\lambda^* : \bar{U} \rightarrow Y, \lambda \in [0, 1]$, by

$$H_\lambda^* = H(x, \theta(x)\lambda) \quad \text{for } (x, \lambda) \in \bar{U} \times [0, 1].$$

It is easy to see that $H_\lambda^* : \bar{U} \rightarrow Y$ is inessential. In particular, $H_1 = F$ is inessential, too. The proof is completed. \square

As a consequence of Lemma 3.1 we have:

Theorem 3.3 (Topological transversality theorem). *Let $F, G \in L_{\partial U}(\bar{U}, Y)$ be homotopics maps. Then one of these maps is essential if and only if the other one is.*

Theorem 3.3 is used in the following equivalent form:

Theorem 3.4 (Topological transversality theorem). *Let Y be a convex subset of a Banach space E , and $U \subset Y$ be open. Suppose:*

- (i) $F, G : \bar{U} \rightarrow Y$ are compact maps;
- (ii) $G \in L_{\partial U}(\bar{U}, Y)$ is essential;
- (iii) $H_\lambda(x), \lambda \in [0, 1]$, is a compact homotopy joining F and G ,
i. e. $H_0(x) = G(x), H_1(x) = F(x)$;
- (iv) $H_\lambda(x), \lambda \in [0, 1]$, is a fixed point free on ∂U .

Then $H_\lambda, \lambda \in [0, 1]$, has at least one fixed point $x_0 \in U$, and, in particular, there is an $x_0 \in U$ such that $x_0 = F(x_0)$.

4. A BASIC EXISTENCE RESULT, ANCILLARY RESULTS

The following theorem is a modification of [8, Chapter II, Theorem 6.1].

Theorem 4.1. *Let $\varphi, \psi : R^4 \rightarrow R$ be continuous. Assume there are constants Q, Q_1, Q_2 (independent of λ) and functions $L(t), F(t) \in C[0, 1]$ (independent of λ) such that:*

- (i) $|x(t)| < Q, F(t) < x'(t) < L(t), Q_1 < x''(t) < Q_2, t \in [0, 1]$, for each solution $x(t) \in C^2[0, 1]$ to $(1.1)_\lambda$ (with fixed $K > 0$) and for $\lambda \in [0, 1]$;

(ii) $f(t, x, p, q)$ and $f_q(t, x, p, q)$ are continuous, and $f_q(t, x, p, q) < 0$ on

$$\left\{ (t, x, p, q) : x \in [-Q, Q], q \in [Q_1, Q_2], t \in [0, 1] \text{ and } p \in [F(t), L(t)] \right\}.$$

(iii) $F(\lambda, t, x, p, Q_1)F(\lambda, t, x, p, Q_2) \leq 0$ for $(\lambda, t, x, p) \in \Lambda =$

$$\left\{ (\lambda, t, x, p) : \lambda \in [0, 1], x \in [-Q, Q], t \in [0, 1] \text{ and } p \in [F(t), L(t)] \right\};$$

Then the BVP (1.1) has at least one $C^2[0, 1]$ -solution.

Proof. From (ii) and (iii) it follows that there is an unique function $G(\lambda, t, x, p)$ continuous on Λ and such that

$$q = G(\lambda, t, x, p) \text{ for } (\lambda, t, x, p) \in \Lambda$$

is equivalent to the equation $F(\lambda, t, x, p, q) = 0$ on $\Lambda \times [Q_1, Q_2]$. Thus, the family (1.1) $_{\lambda}$ is equivalent to the family of BVPs

$$\begin{cases} x'' = G(\lambda, t, x, x'), & t \in [0, 1], \\ W_i(x) = \lambda V_i(x), & i = 1, 2, \end{cases} \quad (4.1)$$

$\lambda \in [0, 1]$. Note that $F \equiv -Kq$ for $\lambda = 0$ and it yields

$$G(0, t, x, p) = 0 \text{ for } (t, x, p) \in \Omega, \quad (4.2)$$

where $\Omega = \left\{ (t, x, p) : x \in [-Q, Q], t \in [0, 1], \text{ and } p \in [F(t), L(t)] \right\}$.

Define the map

$$L_1 : C^2[0, 1] \rightarrow C[0, 1] \times R^2 \quad \text{by} \quad L_1 x = (x'', W_1(x), W_2(x))$$

and the maps

$$G_{\lambda} : C^1[0, 1] \rightarrow C[0, 1] \times R^2 \quad \text{by}$$

$$G_{\lambda}(x) = (G(\lambda, t, x, x'), \lambda V_1(x), \lambda V_2(x)) \quad \text{for } \lambda \in [0, 1].$$

It is easy to see that L_1 is a continuous, linear, one-to-one map of $C^2[0, 1]$ onto $C[0, 1] \times R^2$. So L_1 has a continuous inverse L_1^{-1} . Finally, define $j : C^2[0, 1] \rightarrow C^1[0, 1]$ by $jx = x$, which is a completely continuous embedding.

Now define the set

$$U = \left\{ x \in C^2[0, 1] : \text{for } t \in [0, 1], |x(t)| < M, F(t) < x'(t) < L(t), Q_1 < x''(t) < Q_2 \right\}$$

and consider the homotopy

$$H : \bar{U} \times [0, 1] \rightarrow C^2[0, 1] \text{ defined by } H(x, \lambda) \equiv H_{\lambda}(x) \equiv L_1^{-1} \circ G_{\lambda} \circ j(x).$$

This homotopy is compact since $j(\bar{U})$ is a compact subset of $C^1[0, 1]$, and G_{λ} , $\lambda \in [0, 1]$, and L_1^{-1} are continuous on $j(\bar{U})$ and $G_{\lambda}(j(\bar{U}))$, respectively. In addition, the equation

$$L_1^{-1} \circ G_{\lambda} \circ j(x) = x \quad \text{yields} \quad L_1(x) = G_{\lambda}(x),$$

which is the BVPs (4.1). Then it follows from (i) that $H_{\lambda}(x)$ is a fixed point free on ∂U , i. e. $H_{\lambda}(x)$ is an admissible map for all $\lambda \in [0, 1]$. Finally, $H_0 = 0$ by (4.2).

So H_0 is an essential map by [8, Chapter I, Theorem 2.2]. Now we are in a position to apply Theorem 3.4. It implies that $H_1 = L_1^{-1} \circ G_1 \circ j$ is essential, too, which means that the original problem (1.1) has a solution in $C^2[0, 1]$. \square

The next results prepare the application of Theorem 4.1. They guarantee the a priori bounds from (i) of Theorem 4.1.

Lemma 4.1.A. *Let (A_1) hold for some constants M_1 and M_2 (i. e. (A_1) holds for $F(t) \equiv M_1$ and $L(t) \equiv M_2$, $t \in [0, 1]$). Suppose $x(t) \in C^2[0, 1]$ is a solution to $(1.1)_\lambda$ (with the constant K from (A_1)) such that $M_1 \leq x'(1) \leq M_2$. Then*

$$F_1^-(t) \leq x'(t) \leq L_1^+(t) \quad \text{for } t \in [0, 1].$$

Proof. Suppose the set

$$S_0 = \{t \in [0, 1] : L_1^+(t) < x'(t) \leq L_2^+(t)\}$$

or

$$S_1 = \{t \in [0, 1] : F_2^-(t) \leq x'(t) < F_1^-(t)\}$$

is not empty. The continuity of $x'(t)$ and the inequalities $F_1^-(1) \leq x'(1) \leq L_1^+(1)$ imply that there are closed intervals

$$[t_0, t'_0] \subseteq S_0 \quad \text{or} \quad [t_1, t'_1] \subseteq S_1$$

such that

$$x'(t_0) > x'(t'_0) \quad \text{or} \quad x'(t_1) < x'(t'_1). \quad (4.3)$$

On the other hand, by Lemma 2.1, we have

$$x''(t) \geq 0 \text{ for } t \in [t_0, t'_0] \quad \text{or} \quad x''(t) \leq 0 \text{ for } t \in [t_1, t'_1].$$

Consequently,

$$x'(t_0) \leq x'(t'_0) \quad \text{or} \quad x'(t_1) \geq x'(t'_1).$$

The contradiction to (4.3) shows that S_0 and S_1 are empty, which yields the lemma. \square

Lemma 4.1.B. *Let (A_1) hold for some constants M_1 and M_2 and (B) hold for $L(t) \equiv L_1^+(t)$, $F(t) \equiv F_1^-(t)$, $t \in [0, 1]$, and $M = C + N$, where C is the constant (2.2), N is some constant, and the functions $L_1^+(t)$ and $F_1^-(t)$ are from the condition (A_1) . Suppose $x(t) \in C^2[0, 1]$ is a solution to $(1.1)_\lambda$ (with K from (A_1)) such that*

$$|x(0)| \leq N, t \in [0, 1], \quad \text{and} \quad M_1 \leq x'(1) \leq M_2.$$

Then

$$|x(t)| \leq M \quad \text{for } t \in [0, 1] \quad (4.4)$$

and

$$\min\{H_1^+(1), H_1^-(0)\} \leq x''(t) \leq \max\{G_1^+(0), G_1^-(1)\}, \quad t \in [0, 1]. \quad (4.5)$$

Proof. In fact $C = \max \{ \|L_1^+\|_0, \|F_1^-\|_0 \}$. By the mean value theorem there is $d \in (0, 1)$ such that $x''(d) = x'(1) - x'(0)$. Lemma 4.1.A implies

$$F_1^-(t) \leq x'(t) \leq L_1^+(t) \quad \text{for } t \in [0, 1],$$

i. e. $|x'(t)| \leq C$ for $t \in [0, 1]$. So

$$x''(d) \leq 2C \leq G_1^+(t) \quad \text{for } t \in [0, d]. \quad (4.6)$$

On the other hand, for each $t \in (0, d]$ there is $c \in (0, t)$ such that

$$x(t) - x(0) = x'(c)t,$$

which yields

$$|x(t)| \leq M \quad \text{for } t \in [0, d].$$

Now suppose the set

$$S = \{t \in [0, d] : G_1^+(t) < x''(t) \leq G_2^+(t)\}$$

is not empty. The continuity of $x''(t)$ and (4.6) imply that there is a closed interval

$$[t_0, t'_0] \subseteq S \quad \text{such that } x''(t_0) > x''(t'_0). \quad (4.7)$$

Since for $t \in [t_0, t'_0]$

$$-M \leq x(t) \leq M, \quad F_1^-(t) \leq x'(t) \leq L_1^+(t), \quad G_1^+(t) < x''(t) \leq G_2^+(t),$$

we have

$$f_q(t, x(t), x'(t), x''(t)) < 0, \quad t \in [t_0, t'_0], \quad (4.8)$$

and

$$f_t(t, x(t), x'(t), x''(t)) + f_x(t, x(t), x'(t), x''(t))x' + f_p(t, x(t), x'(t), x''(t))x'' \geq 0$$

for $t \in [t_0, t'_0]$. From the differential equation (1.1) $_\lambda$ for $t \in [t_0, t'_0]$ we obtain

$$\begin{cases} [K(1 - \lambda) - \lambda f_q(t, x(t), x'(t), q_h)] [x''(t+h) - x''(t)] \\ = h f_t(P_{1h}) + f_x(P_{2h}) [x(t+h) - x(t)] + f_p(P_{3h}) [x'(t+h) - x'(t)] \\ \rightarrow f_t(P) + f_x(P)x'(t) + f_p(P)x''(t), \end{cases} \quad (4.9)$$

where $(t, x(t), x'(t), x''(t))$ and the points P_{1h} , P_{2h} and P_{3h} tend to P . Because of (4.8) it follows from (4.9) that $x'''(t)$ exists and

$$x''' = \lambda (f_t + f_x x' + f_p x'') / [K(1 - \lambda) - \lambda f_q], \quad (4.10)$$

which yields

$$x'''(t) \geq 0 \quad \text{for } t \in [t_0, t'_0].$$

Then

$$x''(t_0) \leq x''(t'_0),$$

a contradiction to (4.7). Consequently,

$$x''(t) \leq G_1^+(t) \quad \text{for } t \in [0, d].$$

The inequality

$$H_1^-(t) \leq x''(t), \quad t \in [0, d],$$

may be obtained in a similar way.

Similarly, the inequalities

$$|x(t)| \leq M \quad \text{and} \quad H_1^+(t) \leq x''(t) \leq G_1^-(t), \quad t \in [d, 1],$$

may be established. \square

Lemma 4.2.A. *Let (A_2) hold for some constants M_3 and M_4 . Suppose $x(t) \in C^2[0, 1]$ is a solution to $(1.1)_\lambda$ (with the constant K from (A_2)) such that $M_3 \leq x'(0) \leq M_4$. Then*

$$F_1^+(t) \leq x'(t) \leq L_1^-(t) \quad \text{for } t \in [0, 1].$$

Proof. The lemma can be obtained by using Lemma 2.2 and following the proof of Lemma 4.2.A. \square

Lemma 4.2.B. *Let (A_2) hold for some constants M_3 and M_4 , and (B) hold for $L(t) \equiv L_1^-(t)$, $F(t) \equiv F_1^+(t)$, $t \in [0, 1]$, and $M = C + N$, where C is the constant (2.2), N is some constant, and the functions $L_1^-(t)$ and $F_1^+(t)$ are from the condition (A_2) . Suppose $x(t) \in C^2[0, 1]$ is a solution to $(1.1)_\lambda$ (with K from (A_2)) such that*

$$|x(1)| \leq N, \quad t \in [0, 1], \quad \text{and} \quad M_3 \leq x'(0) \leq M_4.$$

Then (4.4) and (4.5) hold with current notations.

Proof. It is not too different from the proof of Lemma 4.1.B. \square

Lemma 4.3.A. *Let (A_1) and (A_2) hold for $F = \min\{0, M_3 - M_2\}$ and $L = \max\{0, M_4 - M_1\}$, where $M_i \in R$, $i = \overline{1, 4}$. Suppose $x(t) \in C^2[0, 1]$ is a solution to $(1.1)_\lambda$ (with $K = \min\{K_1, K_2\}$, where K_i is the "value" of the constant K from (A_i) , $i = 1, 2$) such that*

$$M_1 \leq x(0) \leq M_2 \quad \text{and} \quad M_3 \leq x(1) \leq M_4.$$

Then for $t \in [0, 1]$

$$\min\{F_1^-(0), F_1^+(1)\} \leq x'(t) \leq \max\{L_1^+(0), L_1^-(1)\}.$$

Proof. There is $d \in (0, 1)$ such that

$$x'(d) = x(1) - x(0) = \lambda[\psi(x(0), x'(0), x(1), x'(1)) - \varphi(x(0), x'(0), x(1), x'(1))],$$

from where it follows

$$\min\{0, M_3 - M_2\} \leq \lambda(M_3 - M_2) \leq x'(d)$$

and

$$x'(d) \leq \lambda(M_4 - M_1) \leq \max\{0, M_4 - M_1\}.$$

For $t \in [0, d]$ we have

$$F_1^-(t) \leq x'(t) \leq L_1^+(t), \quad \text{by Lemma 4.1.A,}$$

and for $t \in [d, 1]$ we have

$$F_1^+(t) \leq x'(t) \leq L_1^-(t), \quad \text{by Lemma 4.2.A,}$$

and the assertion follows. \square

Lemma 4.3.B. *Let (A_1) and (A_2) hold for $F = \min\{0, M_3 - M_2\}$ and $L = \max\{0, M_4 - M_1\}$, where $M_i \in R$, $i = \overline{1, 4}$, and (B) hold for*

$$L(t) \equiv \max\{L_1^+(0), L_1^-(1)\}, \quad F(t) \equiv \min\{F_1^-(0), F_1^+(1)\},$$

and $M = C + \max\{|M_1|, |M_2|, |M_3|, |M_4|\}$, where C is the constant (2.2). Suppose $x(t) \in C^2[0, 1]$ is a solution to (1.1) $_\lambda$ (with $K = \min\{K_1, K_2\}$, where K_i is the "value" of the constant K from (A_i) , $i = 1, 2$) such that

$$M_1 \leq x(0) \leq M_2 \quad \text{and} \quad M_3 \leq x(1) \leq M_4.$$

Then (4.4) and (4.5) hold with a current notations.

Proof. It is not too different from the proof of Lemma 4.1.B. \square

5. EXISTENCE RESULTS

Theorem 5.1. *Let $\varphi, \psi : R^4 \rightarrow R$ be continuous. Suppose there are constants M_i , $i = 1, 2$, and N such that:*

- (i) $M_1 \leq \psi(s_1, s_2, s_3, s_4) \leq M_2$ for $(s_1, s_2, s_3, s_4) \in R_4$;
- (ii) (A_1) holds for M_1 and M_2 ;
- (iii) $|\varphi(s_1, s_2, s_3, s_4)| \leq N$ for $(s_1, s_2, s_3, s_4) \in R \times [F_1^-(0), L_1^+(0)] \times R \times [M_1, M_2]$;
- (iv) (B) holds for $L(t) \equiv L_1^+(t)$, $F(t) \equiv F_1^-(t)$, $t \in [0, 1]$, and $M = C + N$, where C is the constant (2.2);
- (v) (C) holds for $L(t) \equiv L_1^+(t) + \varepsilon$, $F(t) \equiv F_1^-(t) - \varepsilon$, $t \in [0, 1]$, for

$$Q = C + N + \varepsilon, \quad Q_1 = \min\{H_1^+(1), H_1^-(0)\} - \varepsilon, \quad Q_2 = \max\{G_1^+(0), G_1^-(1)\} + \varepsilon,$$

where C is the constant (2.2), and ε satisfies (2.4).

Then the mixed BVP (M_1) has a $C^2[0, 1]$ -solution.

Proof. Let $x(t) \in C^2[0, 1]$ be a solution to $(M_1)_\lambda$. Then

$$F_1^-(t) - \varepsilon < x'(t) < L_1^+(t) + \varepsilon \quad \text{for } t \in [0, 1], \text{ by Lemma 4.1.A,}$$

and Lemma 4.1.B yields the bounds

$$|x(t)| < Q \quad \text{for } t \in [0, 1],$$

$$Q_1 < x''(t) < Q_2 \quad \text{for } t \in [0, 1].$$

Then the condition (i) of Theorem 4.1 holds. From (2.5) it follows that the condition (ii) of Theorem 4.1 holds. Finally, (v) implies that the condition (iii) of Theorem

4.1 holds. So we can apply Theorem 4.1 to conclude that the problem (M_1) has a solution in $C^2[0, 1]$. \square

Theorem 5.2. *Let $\varphi, \psi : R^4 \rightarrow R$ be continuous. Suppose there are constant $M_i, i = 3, 4$, and N such that:*

- (i) $M_3 \leq \varphi(s_1, s_2, s_3, s_4) \leq M_4$ for $(s_1, s_2, s_3, s_4) \in R_4$;
- (ii) (A_2) holds for M_3 and M_4 ;
- (iii) $|\psi(s_1, s_2, s_3, s_4)| \leq N$ for $(s_1, s_2, s_3, s_4) \in R \times [M_3, M_4] \times R \times [F_1^+(1), L_1^-(1)]$;
- (iv) (B) holds for $L(t) \equiv L_1^-(t), F(t) \equiv F_1^+(t), t \in [0, 1]$, and $M = C + N$, where C is the constant (2.2);
- (v) (C) holds for $L(t) \equiv L_1^-(t) + \varepsilon, F(t) \equiv F_1^+(t) - \varepsilon, t \in [0, 1]$, for

$$Q = C + N + \varepsilon, Q_1 = \min\{H_1^+(1), H_1^-(0)\} - \varepsilon, Q_2 = \max\{G_1^+(0), G_1^-(1)\} + \varepsilon,$$

where C is the constant (2.2), and ε satisfies (2.4).

Then the mixed BVP (M_2) has a $C^2[0, 1]$ -solution.

Proof. It is not too different from the proof of Theorem 5.1. Consider $(M_2)_\lambda$. Now Lemma 4.2.A guarantees the a priori bound for x' , and Lemma 4.2.B guarantees the a priori bounds for x and x'' . \square

Theorem 5.3. *Let $\varphi, \psi : R^4 \rightarrow R$ be continuous. Suppose there are constants $M_i, i = \overline{1, 4}$, such that:*

- (i) $M_1 \leq \varphi(s_1, s_2, s_3, s_4) \leq M_2$ and $M_3 \leq \psi(s_1, s_2, s_3, s_4) \leq M_4$ for $(s_1, s_2, s_3, s_4) \in R_4$;
- (ii) (A_1) and (A_2) hold for $F = \min\{0, M_3 - M_2\}$ and $L = \max\{0, M_4 - M_1\}$;
- (iii) (B) holds for $L(t) \equiv \max\{L_1^+(0), L_1^-(1)\}, F(t) \equiv \min\{F_1^-(0), F_1^+(1)\}$ and $M = C + \max\{|M_1|, |M_2|, |M_3|, |M_4|\}$, where C is the constant (2.2);
- (iv) (C) holds for the functions

$$L(t) \equiv \max\{L_1^+(0), L_1^-(1)\} + \varepsilon, F(t) \equiv \min\{F_1^-(0), F_1^+(1)\} - \varepsilon,$$

$$Q = C + \max\{|M_1|, |M_2|, |M_3|, |M_4|\} + \varepsilon, Q_1 = \min\{H_1^+(1), H_1^-(0)\} - \varepsilon,$$

$$Q_2 = \max\{G_1^+(0), G_1^-(1)\} + \varepsilon,$$

where C is the constant (2.2), and ε satisfies (2.4).

Then the Dirichlet BVP (D) has a $C^2[0, 1]$ -solution.

Proof. It is not too different from the proof of Theorem 5.1. Now consider the family $(D)_\lambda$. The a priori bound for x' follows by Lemma 4.3.A, and the a priori bounds for x and x'' follow by Lemma 4.3.B. \square

6. EXAMPLES

Example 6.1. Consider the boundary value problem

$$\begin{aligned} -(2-t)x'' - tx''^3 + \sin(x' - 0.2) &= 0, \quad t \in [0, 1], \\ x(0) = 0, \quad x'(1) &= 0.15. \end{aligned}$$

For $L = F = 0.15$ (A_1) holds. Moreover, we can choose

$$L_1^+(t) = 0.25, \quad L_2^+(t) = 0.3, \quad F_1^-(t) = 0.1, \quad F_2^-(t) = 0.05, \quad t \in [0, 1],$$

and K is sufficiently small; to say $K = 10^{-10}$. It is easy to see that $f_q = -(2-t)q - 3tq^2 < 0$ for $t \in [0, 1]$ and each q . This fact allows us to conclude that (B) holds for $L(t) = 0.25$, $F(t) = 0.1$, $t \in [0, 1]$, and $M = 0.25$. Moreover, we can choose

$$\begin{aligned} G_1^+(t) = 0.9, \quad G_2^+(t) = 1, \quad G_1^-(t) = 2, \quad G_2^-(t) = 3, \\ H_1^-(t) = -0.9, \quad H_2^-(t) = -1, \quad H_1^+(t) = -2, \quad H_2^+(t) = -3, \quad t \in [0, 1]. \end{aligned}$$

Finally, from

$$2.01(\lambda - 1)K + \lambda [-2.01(2-t) - (2.01)^3t + \sin(p - 0.2)] \leq 0$$

and

$$-2.01(\lambda - 1)K + \lambda [-(-2.01)(2-t) - (-2.01)^3t + \sin(p - 0.2)] \geq 0$$

for $\lambda, t \in [0, 1]$ and each p we conclude that (C) holds for $Q_1 = -2.01$ and $Q_2 = 2.01$. Thus the problem considered has a $C^2[0, 1]$ -solution by Theorem 5.1.

Example 6.2. Consider the boundary value problem

$$\begin{aligned} x'^2 - 4 - 50(2-t)x'' - tx''^5 &= 0, \quad t \in [0, 1], \\ x(0) = [x^2(0) + x'^2(0) + x^2(1) + x'^2(1) + 1]^{-1}, \quad x(1) &= \sin^2 x'(1). \end{aligned}$$

For $L = 1$ and $F = -1$ (A_1) and (A_2) hold. Moreover, we can choose

$$\begin{aligned} L_1^+(t) = 2.1, \quad L_2^+(t) = 2.2, \quad F_1^-(t) = -1.1, \quad F_2^-(t) = -1.2, \\ L_1^-(t) = 1.1, \quad L_2^-(t) = 1.2, \quad F_1^+(t) = -2.1, \quad F_2^+(t) = -2.2, \quad t \in [0, 1], \end{aligned}$$

and K is sufficiently small; to say $K = 10^{-10}$. It is easy to see that $f_q = -50(2-t) - 5q^4t < 0$ for $t \in [0, 1]$ and each q . Thus (B) holds for $L(t) = 2.1$, $F(t) = -2.1$, $t \in [0, 1]$ and, $M = 3.1$. Moreover, we can choose

$$\begin{aligned} G_1^+(t) = 6.5, \quad G_2^+(t) = 6.6, \quad G_1^-(t) = 10, \quad G_2^-(t) = 11, \\ H_1^-(t) = -6.5, \quad H_2^-(t) = -6.6, \quad H_1^+(t) = -10, \quad H_2^+(t) = -11, \quad t \in [0, 1]. \end{aligned}$$

Finally, from

$$10.01(\lambda - 1)K + \lambda [p^2 - 4 - 50(2-t)10.01 - (10.01)^5t] \leq 0$$

and

$$-10.01(\lambda - 1)K + \lambda [p^2 - 4 - 50(2-t)(-10.01) - (-10.01)^5t] \geq 0$$

for $\lambda, t \in [0, 1]$ and $p \in [-3.11, 3.11]$ we conclude that (C) holds for $L(t) = 2.11$, $F(t) = -2.11$, $t \in [0, 1]$, $Q = 3.11$, $Q_1 = -10.01$ and $Q_2 = 10.01$; $\varepsilon = 0.01$. Thus the problem considered has a $C^2[0, 1]$ -solution by Theorem 5.3.

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PETIO KELEVEDJIEV

Technical University of Sliven

59 Bourgasko Chaussee str.

8800 Sliven, Bulgaria

E-mail: keleved@mailcity.com

NEDYU POPIVANOV

“St. Kl. Ohridski” University of Sofia

5 James Bourchier Blvd 5, POBox 48

1164 Sofia, Bulgaria

E-mail: nedyu@fmi.uni-sofia.bg